```
from grove.i2c import Bus
import time

HM3301_WRITE_ADDR                = 0x80
HM3301_READ_ADDR                 = 0x81
HM3301_SELECT_COMM_CMD     = 0x88
HM3301_ADDR                          = 0x40
HM3301_DATA_BYTES_LENGTH     = 29

class GroveLaserPM25HM3301():
    def __init__(self, bus=None, address=HM3301_ADDR):
        self.I2CAddress = address
        self.bus = Bus(bus)

    #Turn off UART communication by sending the command to notify
    #the sensor to only use I2C
    def initialize(self):
        self.bus.write_byte_data(self.I2CAddress, HM3301_WRITE_ADDR, HM3301_SELECT_COMM_CMD)

    def readValues(self):
        return self.bus.read_i2c_block_data(self.I2CAddress, HM3301_READ_ADDR, HM3301_DATA_BYTES_LENGTH)

    if __name__ == "__main__":
        test = GroveLaserPM25HM3301()
        test.initialize()
        check = test.readValues()
```